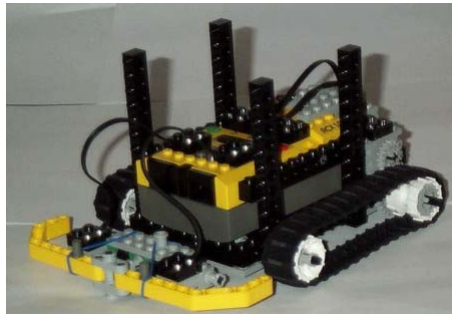


Messwerverfassung mit Lego-Robolab

Veranstalter: Bezirksregierung
Köln

März 2007

Leitung: Bastgen / Stein
Referent: Peter Bastgen



DCP-Sensoren



[Startseite]



[Projektauswahl]



[Programmieroberfläche]



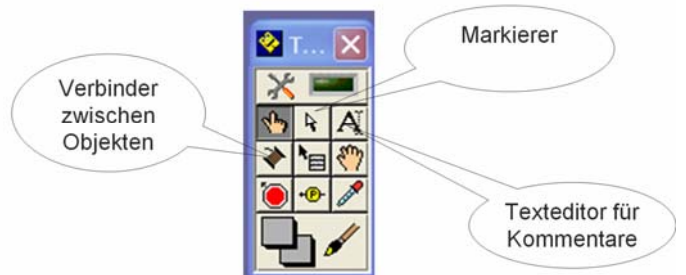
[Arbeitsfläche leer]



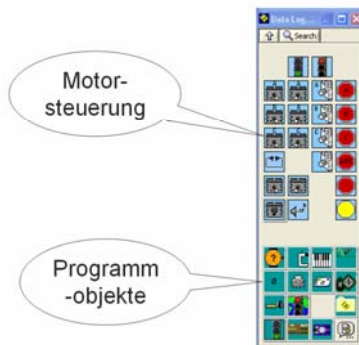
[Arbeitsfläche]



[Werkzeugkiste]



[Motoren und ...]



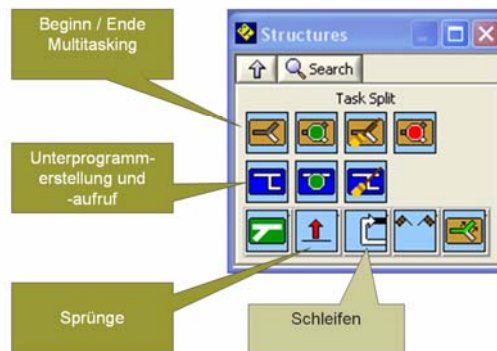
[Programmobjekte]



[Warten bis ...]



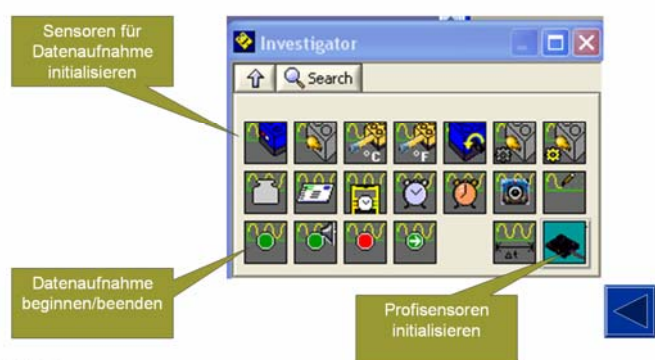
[Strukturen]



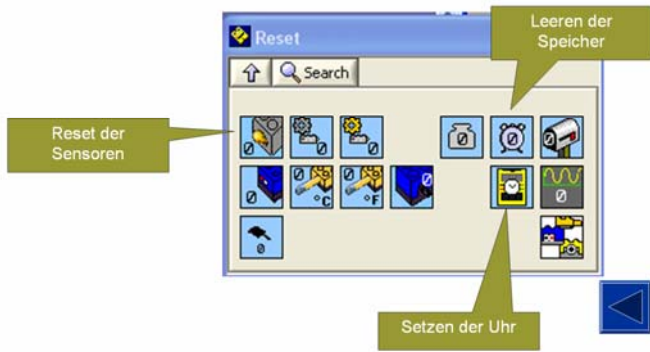
[Schleifen]



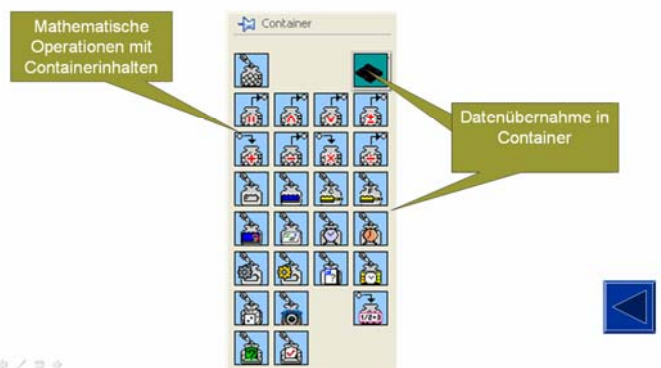
[Investigator]



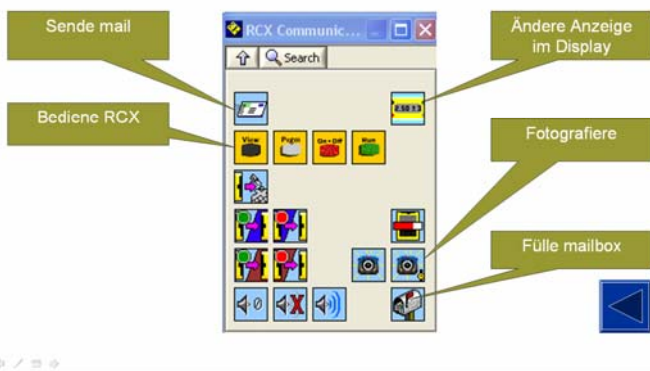
Reset



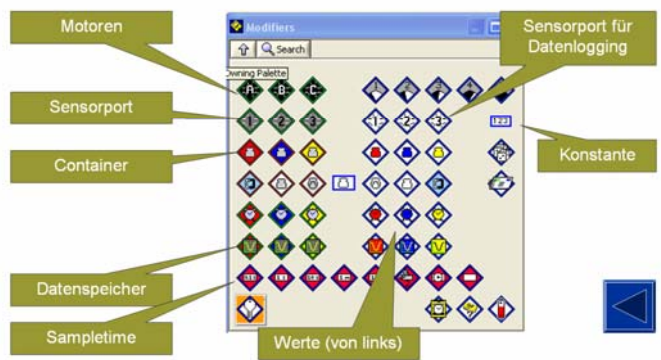
Container



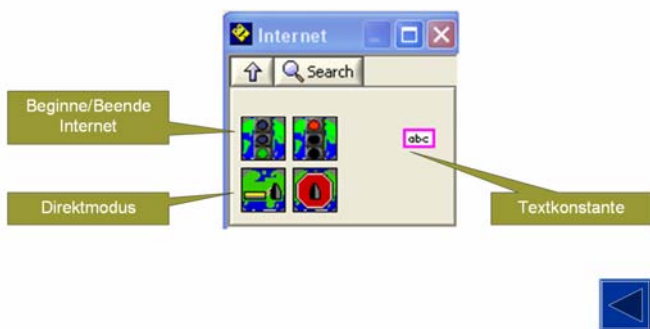
RCX-Kommunikation



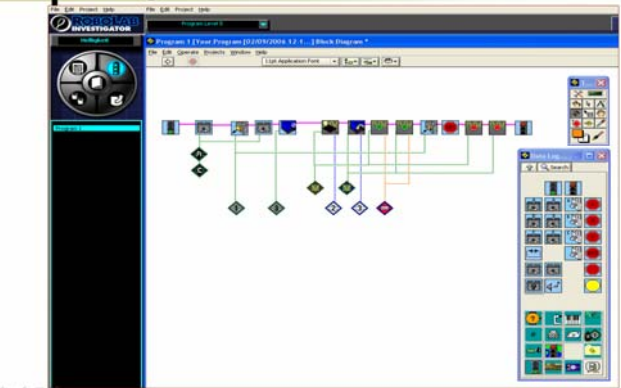
Modifizier



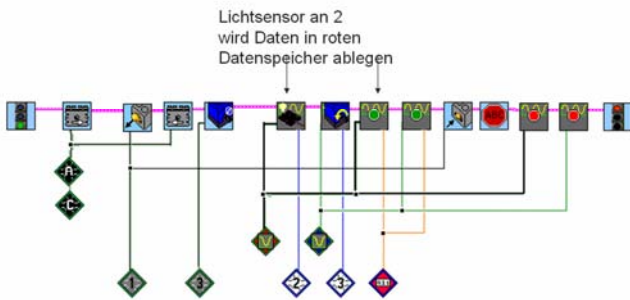
Internet



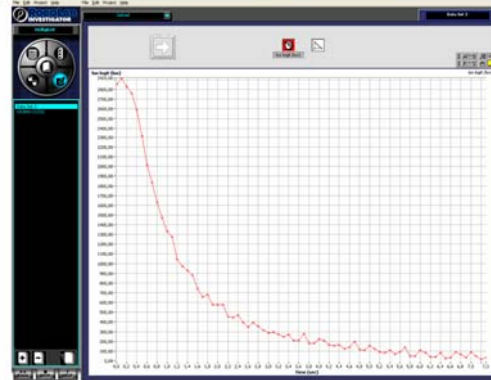
Helligkeit als Fkt. des Abstandes



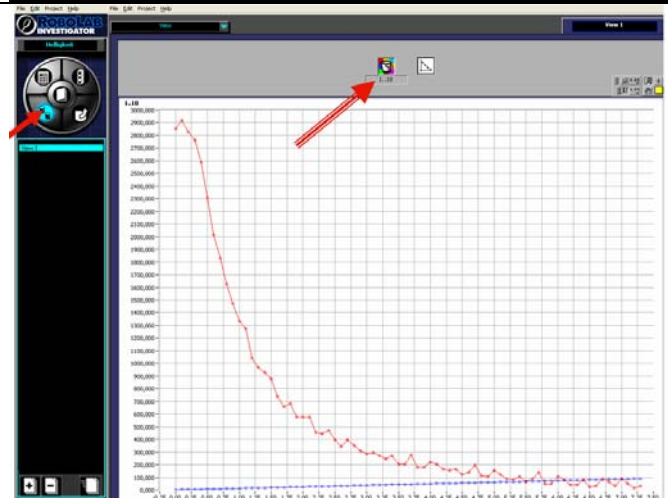
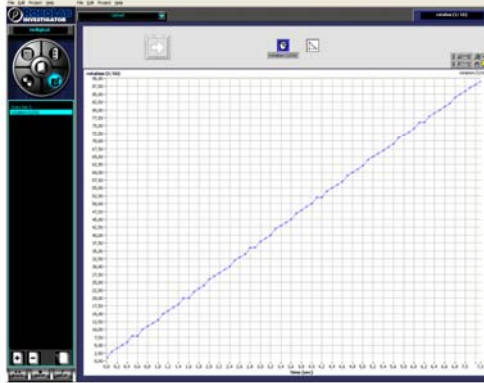
Helligkeit als Fkt. des Abstandes



Upload der Helligkeit



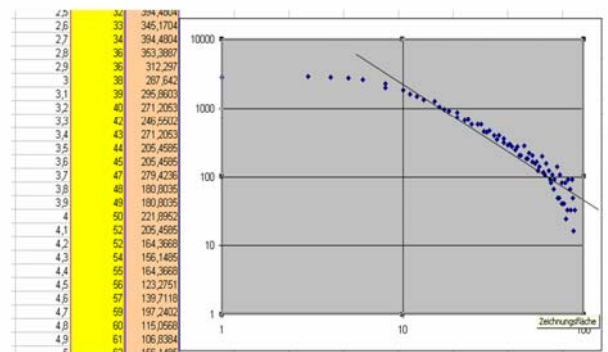
Upload des Rotationssensors



Speichern der Werte in Txt-Datei



Import nach Excel



Infos unter: <http://technik-lpe.de>
http://www.mindstormsforum.de/mediawiki/index.php?title=Andere_Sensoren
<http://www.gymnasium-wertingen.de/deutsch/fachbereiche/informatik/material/RoboLab/>